

Basil Dissi

(252)-367-0167

[LinkedIn](#) | [Github](#) | [basildissi.dev](#)

basildissi@gmail.com

EDUCATION

Georgia Institute of Technology

Expected January 2027

M.S. in Computer Science

GPA: 4.0 | Magna Sum Laude

North Carolina State University

May 2021

B.S. in Biomedical Engineering

GPA: 3.69 | Magna Cum Laude

SKILLS & CERTIFICATIONS

Languages: C++, Python, Java, MATLAB, Bash

Systems & Networking: Linux, QNX (RTOS), POSIX threads, shared memory, sockets, real-time systems, DDS (RTI)

Developer Tools & Platforms: Git, Gitlab CI, Conan, CMake, LLVM

Data & Analysis: Pandas, NumPy, SciPy

EXPERIENCE

Product Development Engineer (Software Focused) | Asensus Surgical

January 2022 – Present

- Designed and implemented C++ applications deployed in a real-time (QNX) environment to simulate surgeon motion commands for automated testing of robotic controllers. Used company wide and became a corner stone of SW V&V.
- Built ROS2/DDS-based real-time messaging pipelines enabling synchronized data exchange between simulated environments and physical robotic subsystems
- Developed a motion-capture server to synchronize recorded trajectories with robotic controllers at 1 ms temporal resolution and ~100 μ m positional accuracy
- Implemented software tooling to support integration, calibration, and validation of next-generation force/torque sensors
- Led cross-functional engineering efforts to integrate four 3 mm laparoscopic instruments into a production robotic surgical system, coordinating software, controls, quality, and regulatory stakeholders
- Partnered with manufacturing, regulatory, and quality teams to redesign test strategies, eliminating ~6 months of testing and reducing costs by \$120K+
- Overhauled internal V&V tracking workflows while developing and executing verification strategies for a next-generation robotic system with 400+ system requirements

Research and Development Engineer Intern | Asensus Surgical – Senhance Project

August 2021 – December 2021

- Supported software, electrical, and mechanical verification activities for a Class II robotic surgical system
- Performed root-cause analysis on system-level failures and presented data-driven recommendations to engineering teams
- Authored and executed verification protocols across hardware/software boundaries in a regulated development environment

PROJECTS

Distributed File System/gRPC Service

- Designed and implemented a distributed file system using gRPC, supporting concurrent clients and remote procedure calls
- Implemented consistency mechanisms and synchronization primitives to ensure correctness under concurrent access
- Evaluated performance tradeoffs and failure behavior under varying workloads and network conditions

Multicore Cache Coherence Analysis & Performance Modeling

- Modified a cycle-accurate multicore simulator to classify cache misses into compulsory, replacement, and coherence categories
- Analyzed performance scaling and IPC degradation across 1–16 core configurations
- Identified coherence traffic and synchronization overhead as primary contributors to diminishing parallel efficiency